# Large Eddy Simulation of Turbulent Flow in Continuous Casting of Steel

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![](_page_3_Figure_0.jpeg)

# The Continuous Casting Mold

### **Characteristics of Fluid Flow in the Mold**

- High Reynolds number (Re<sub>inlet</sub> ~ 50,000), swirling multiphase high temperature (T = 1500°C) jet at inlet
- Jet phases include liquid steel, argon gas bubbles and alumina particles
- Impingement of semi-confined jet with high heat transfer rates
- Recirculation region above and below the jet
- Flow field highly turbulent, three dimensional and transient
- Solidification of molten steel at and below the impingement face
- Free surface covered with flux powder

### **Need for Transient Mold Flow Modeling**

- Eliminate defects caused by transient flow phenomena, which affect strand quality
- Entrainment of liquid flux by shear of the liquid layer
- Entrapment of argon gas and alumina particles
- Surface defects
- Improve sensors used to monitor fluid flow in the mold
- Input for subsequent modeling
- Heat transfer
- Solidification
- Thermal stress analysis
- Improve future caster design

### **Tools to Study Transient Fluid Flow**

- Water Modeling
- Flow Visualization
- Particle Image Velocimetry (PIV) Measurements
- Numerical Simulation
- K-ε Models Unsteady
- Large Eddy Simulation (LES) Transient
- Actual Caster
- eg. Electromagnetic Sensors

# Water Modeling

- Kinematic viscosity of molten steel is approximately equal to that of water
- Fluid flow in the caster can be studied using a scaled, transparent, Plexiglas water model
- Take into account steel shell using appropriate taper
- Use Particle Image Velocimetry (PIV) to quantify the fluid flow in the water model
- As a first study perform Large Eddy Simulations (LES) of the fluid flow in the water model

![](_page_8_Figure_0.jpeg)

Water Model

# **Particle Image Velocimetry**

![](_page_9_Figure_1.jpeg)

# **PIV - Principle**

- Tracer particles (negligible mass and momentum coupling) are injected into the flow
- Two closely spaced (time) snapshots are taken using a CCD camera
- Particle locations in two snapshots are correlated to obtain distance moved by particle
- Flow velocity at particle location = Distance/Time

# **PIV Methodology**

#### • **Resolution**

- CCD camera DANTEC Double Image 700 with 768x480 pixels
- Number of pixels per interrogation area 16x16 64x64
- Average of 32x32 used
- 25% overlap used to capture particles near interrogation area edges
- Maximum vectors per measurement area 31x19
- **Time interval between snapsnots** varies from 0.2 1s
- Time interval between correlated frames 100 µs
- Seeding particle Aluminum ( 30µm)
- Correlation technique Autocorrelation

![](_page_11_Figure_11.jpeg)

### **Modifications - Boundary conditions**

- Constant thickness assumed from top to bottom
- Thickness variation is not large enough to justify using more complicated CFD algorithm
- Free water surface simplified to rigid free slip boundary
- Water level variations spatially and temporally are small
- Only half the domain is modeled
- Not enough evidence was available to assume large scale lower roll motions
- A factor of two benefit is obtained in computational size
- Inflow swirl is replaced by fully-developed turbulent flow from square duct
- Modeling swirl would require using an iterative solver (AMG) as opposed to a direct (FFT) solver which would make at least a factor of five difference in computational time
- Helps check hypothesis of flow parameters being sensitive to inlet conditions
- Square duct (LES) helps validate flow code

### **Modifications – Phenomena**

### • Single phase modeling

- Water Model can be run easily in single phase mode to validate model for single phase
- Single phase solution can be used as a easy start point for multiphase modeling

### • Solidification neglected

- Present only deep down in the mold and close to the narrow face and can be neglected when modeling fluid flow
- Will be of significance when modeling heat transfer

### Heat Transfer neglected

- Secondary calculation if Boussinesq approximation is invoked
- Like multiphase can be solved for when fluid flow phenomenon have been captured

![](_page_14_Figure_0.jpeg)

### **Computational Flow Simulation Domain**

# **Large Eddy Simulation Model**

Continuity 
$$\frac{\partial v_j}{\partial x_j} = 0$$
  
Momentum  $\frac{\partial}{\partial t}\rho v_i + \frac{\partial}{\partial x_j}\rho v_j v_i = -\frac{\partial P}{\partial x_i} + \frac{\partial}{\partial x_j}\mu_{eff}\left(\frac{\partial v_j}{\partial x_i} + \frac{\partial v_i}{\partial x_j}\right)$ 

Smagorinsky Model

$$-\tau_{ij}\overline{S_{ij}} = \varepsilon = v_T \overline{S_{ij}}\overline{S_{ij}}; v_T \sim \ell q_{SGS}$$
$$q_{SGS}^2 \sim \ell^2 \overline{S_{ij}}\overline{S_{ij}}$$
$$v_T = (C_S \Delta^2) |\overline{S}|$$
$$|\overline{S}| = (2\overline{S_{ij}}\overline{S_{ij}})^{1/2}$$

### Large Eddy Simulation Methodology

- The equations are discretized using a fractional step procedure on a staggered grid
- A Second order accurate scheme in time and space is used
- The implicit diffusion terms are solved for using Fast Fourier Transform (FFT) and Alternate Line Inversion (ALI)
- The Pressure-Poisson equation is solved using direct FFT
- For parallelization 1-D domain decomposition with MPI (Message Passing Interface) is used
- Rectangular computational grid of 1.5 million nodes
- 18 CPU secs per 0.001s time step or
  13 days CPU time (Origin 2000) for 60s of flow simulation

### **Flow Pattern and Jet Angle**

![](_page_17_Picture_1.jpeg)

# **Asymmetry Between Jets**

![](_page_18_Picture_1.jpeg)

![](_page_19_Figure_0.jpeg)

![](_page_20_Figure_0.jpeg)

# Time Average Comparison

### **Staircase Effect in Experimental Jet**

![](_page_21_Figure_1.jpeg)

# **Simulation Jet**

![](_page_22_Figure_1.jpeg)

![](_page_23_Figure_0.jpeg)

### **Staircase Effect and Time Scales**

![](_page_24_Figure_1.jpeg)

T+0.4 s

![](_page_24_Figure_3.jpeg)

![](_page_24_Figure_4.jpeg)

![](_page_24_Figure_5.jpeg)

## **Shallow Penetrating Jet**

![](_page_25_Figure_1.jpeg)

### **Large Time Scale Motion**

![](_page_26_Figure_1.jpeg)

# **Upper Roll Structure**

![](_page_27_Figure_1.jpeg)

### **Upper Roll Structure**

![](_page_28_Figure_1.jpeg)

### **Velocity Time History Near Water Surface**

![](_page_29_Figure_1.jpeg)

![](_page_30_Picture_0.jpeg)

# Simulation Jet - Structure and Spread

# Sensor (MFC) on Caster

![](_page_31_Figure_1.jpeg)

![](_page_32_Figure_0.jpeg)

Instantaneous Flow Past Sensor

![](_page_33_Figure_0.jpeg)

![](_page_33_Figure_1.jpeg)

![](_page_33_Figure_2.jpeg)

Qualitative Comparison of Sensor Outputs

# **Asymmetry in Lower Rolls**

![](_page_34_Figure_1.jpeg)

# **Lower Roll Transients**

![](_page_35_Figure_1.jpeg)

![](_page_35_Figure_2.jpeg)

### **Right Roll Larger**

### **Rolls Same Size**

## **Results - Summary**

- Jet vector plots show a staircase pattern caused by the inlet swirl (PIV)
- The jet has many different time scales of motion (PIV)
- Velocity variation close to the water surface has two time scales (PIV and LES)
- Upper roll alternates between a single recirculation region and a set of distinct vortices (PIV and LES).
- MFC sensor should be placed close to the water surface for accurate interpretation
- Lower rolls are significantly asymmetric (PIV)
- Lower rolls go through a repeating sequence of flow structures (PIV)
- The short-circuit structure is significant to **particle entrapment**

## **Table of Conditions**

No.	Property	Water model	Simulation
1	Length of the model	0.950m	0.956m
2	Thickness of model	Varies from 0.095m	Constant
		at the top to 0.065m	0.08m
3	Port opening	0.031 x 0.031m	0.031 x 0.031m
4	Top surface	Free surface	Free slip boundary
5	Flow rate through each port	$3.528 \text{ x } 10^{-4} \text{ m}^{3}/\text{s}$	$3.528 \times 10^{-4} \text{ m}^3/\text{s}^3$
		(5.6 gal/min)	(5.6 gal/min)
6	Average inlet velocity	0.4239m/s	0.4239m/s
7	Average jet inlet angle	$30^{\circ}$	$30^{\circ}$
8	Distance of top of port outlet from	0.075 m	0.07207m
	top surface (submergence depth)	(Varies with time)	
9	Outlet	1.5 35mm diameter	1.5 35mm square
		outlets along each	outlets at the
		half of the bottom	bottom
10	Fluid used	Water	Water
11	Kinematic viscosity	$1 \ge 10^{-6} \text{ m}^2/\text{s}$	$1 \ge 10^{-6} \text{ m}^2/\text{s}$
12	Gas flow rate (cubic ft / hr)	0.0	0.0